

Lecture 13

Prop Any CNOT+phase circuit describes a unitary of the form:

$$U :: |\vec{x}\rangle \mapsto e^{i\phi(\vec{x})} |L\vec{x}\rangle$$

↑ phase polynomial
↑ parity matrix.

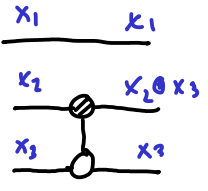
From the example above: $L = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}$ and

$$\phi(x_1, x_2, x_3) = (\alpha + \gamma) \cdot (x_2 \oplus x_3) + \beta \cdot (x_1 \oplus x_2) + \theta \cdot x_2$$

↑ phase-folding

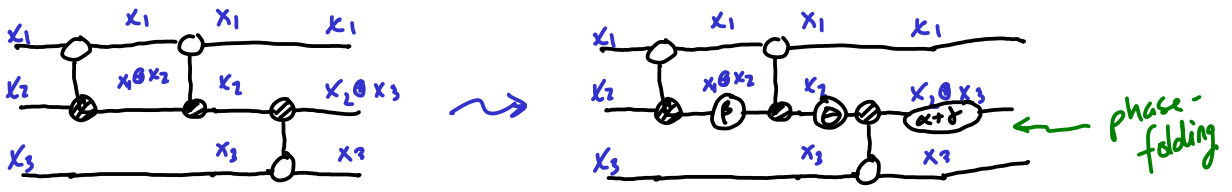
Q: can we re-synthesise a circuit for (L, ϕ) ?

For L , we have:



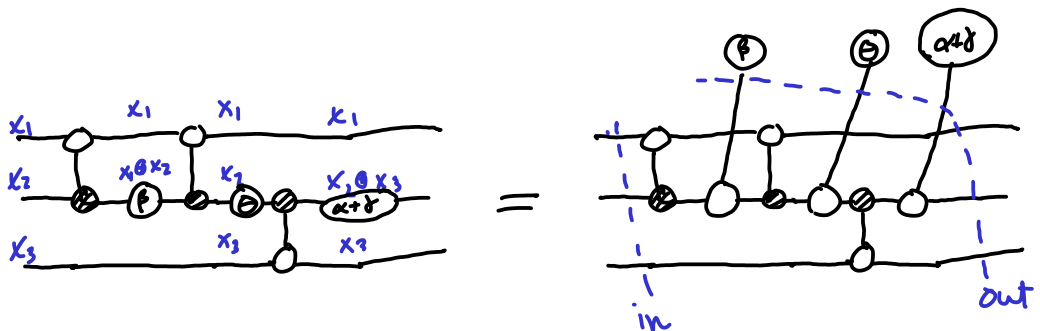
To get ϕ , we need to place Z-phases on wires labelled: $x_2 \oplus x_3$, $x_1 \oplus x_2$, and x_2

Only $x_1 \oplus x_2$ is missing, so lets (temporarily) create it:



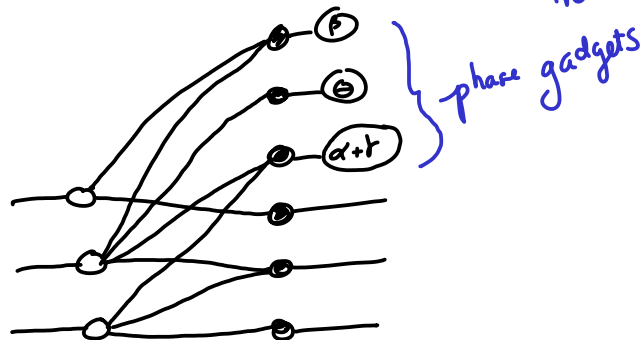
Phase polynomials, graphically (aka. phase gadgets)

Ex



phase-free simp.

=



1-legged:

$$\text{---} \textcircled{\alpha} \text{---} :: |x\rangle \mapsto \begin{cases} 1 & \text{if } x=0 \\ e^{i\alpha} & \text{if } x=1 \end{cases} = e^{i\alpha \cdot x}$$

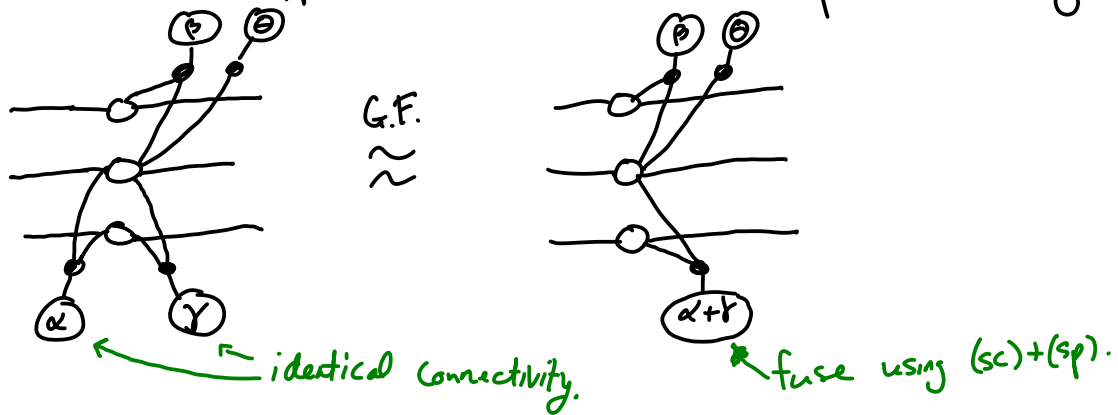
k-legged phase gadget:

$$\sqrt{2}^{(k-1)} \text{---} \textcircled{\alpha} \text{---} :: |x_1 \dots x_k\rangle \mapsto e^{i\alpha \cdot (x_1 \oplus \dots \oplus x_k)}$$

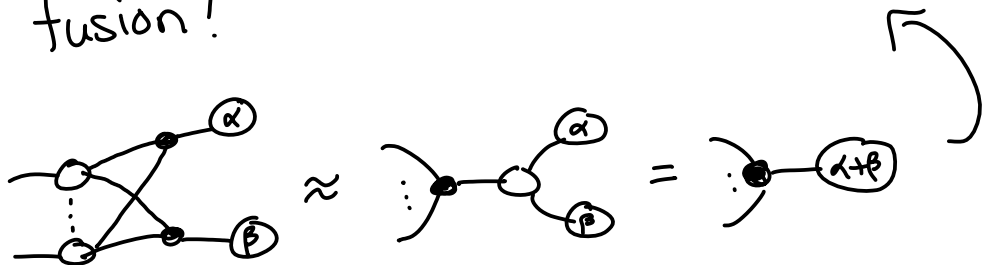
In a diagonal unitary:

$$\sqrt{2}^{(k-1)} \text{---} \textcircled{\alpha} \text{---} :: |x_1 \dots x_k\rangle \mapsto e^{i\alpha \cdot (x_1 \dots x_k)} |x_1 \dots x_k\rangle$$

Q: What happens when there is phase folding?



A: Gadget fusion!

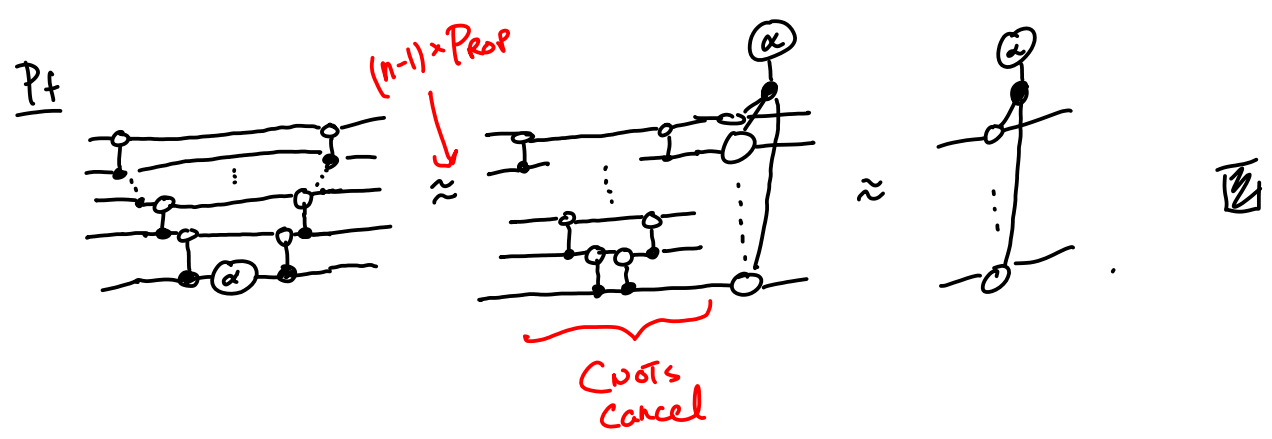
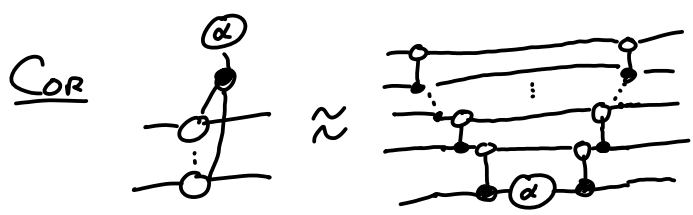
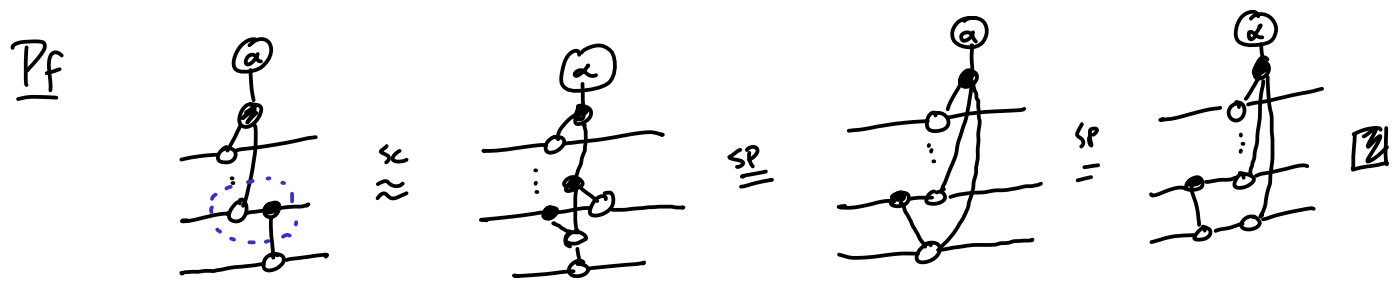
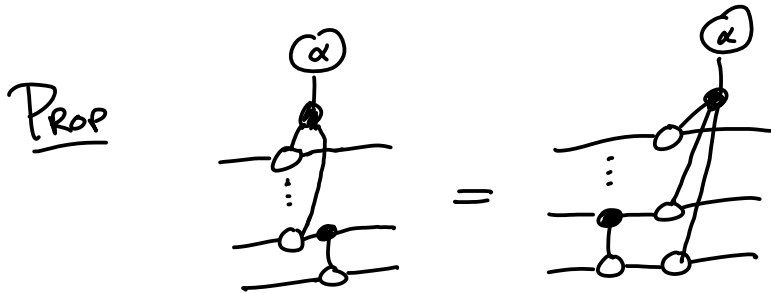


Algorithm: CNOT + phase optimisation.

1. unfuse phases and treat as outputs.
2. Compute PNF of phase-free part.
3. perform gadget fusion (* and other phase-poly reductions!)
- ?? → 4. extract a CNOT + phase circuit.

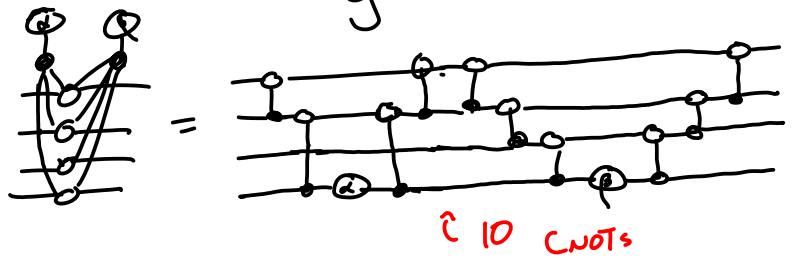
There are choices for step 4.

Naïve approach: "CNOT ladders"

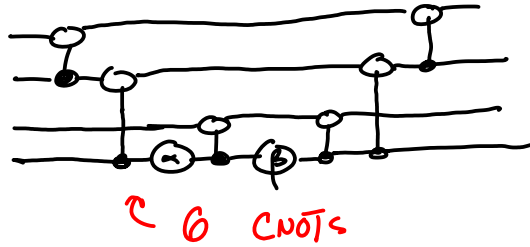


Naïve extraction: 1. unfuse a phase gadget + replace using Cor 1.
 2. repeat until no phase gadgets
 3. synthesise CNOT circuit from phase-free diag.

* Lots of wasted CNOT gates! e.g.

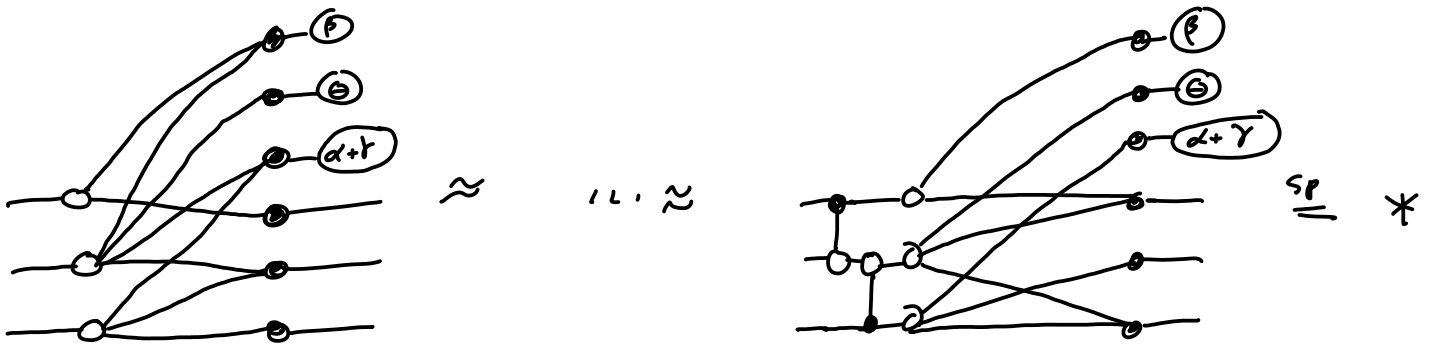


Vs.



"T-par" style extraction [Amy, Maslov, Mosca 2013]

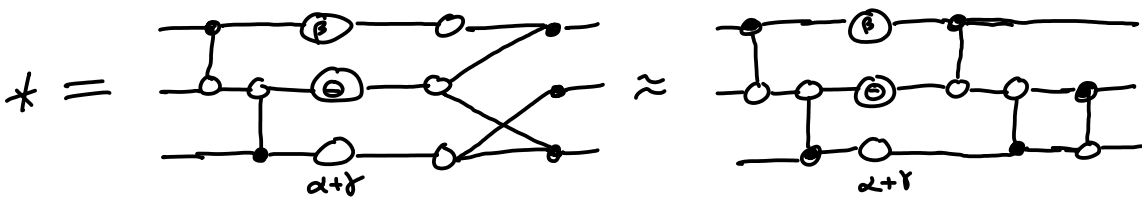
1. write an "extended biadjacency matrix"
2. identify a set of k linearly independent rows
3. reduce each row to a unit vector with column ops.
4. "extract phases" and repeat.



gadgets {

outputs {

$$\begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 1 \\ \hline 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} \xrightarrow{C_2 = C_2 + C_1} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} \xrightarrow{C_2 = C_2 + C_3} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ \hline 1 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 1 \end{pmatrix}$$



$$\begin{pmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 1 \end{pmatrix} \xrightarrow{C_2 = C_2 + C_1} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 1 \end{pmatrix} \xrightarrow{C_2 = C_2 + C_3} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} \xrightarrow{C_3 = C_3 + C_2} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Pros: · very good at low non-Clifford depth (i.e. layers of non-Cliff gates).

· gets better with ancilla!

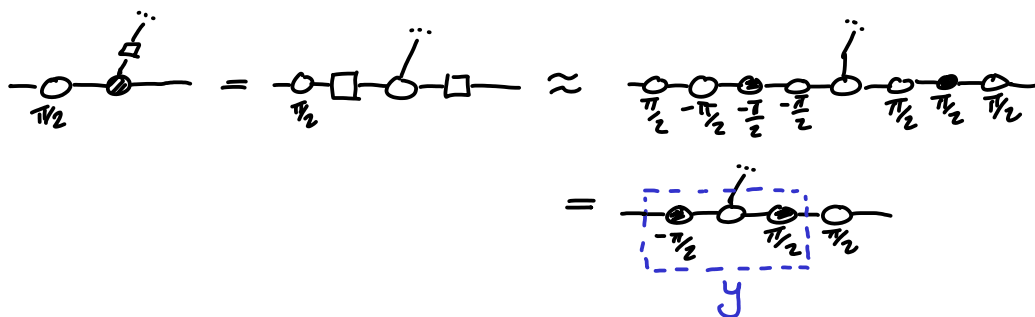
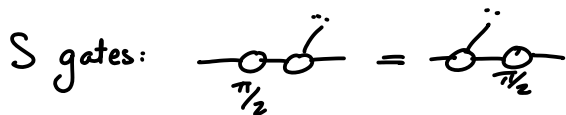
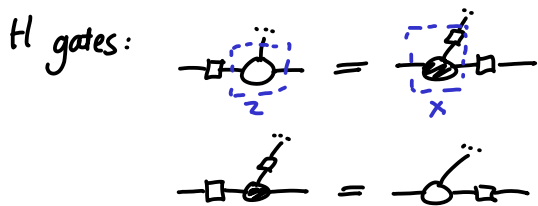
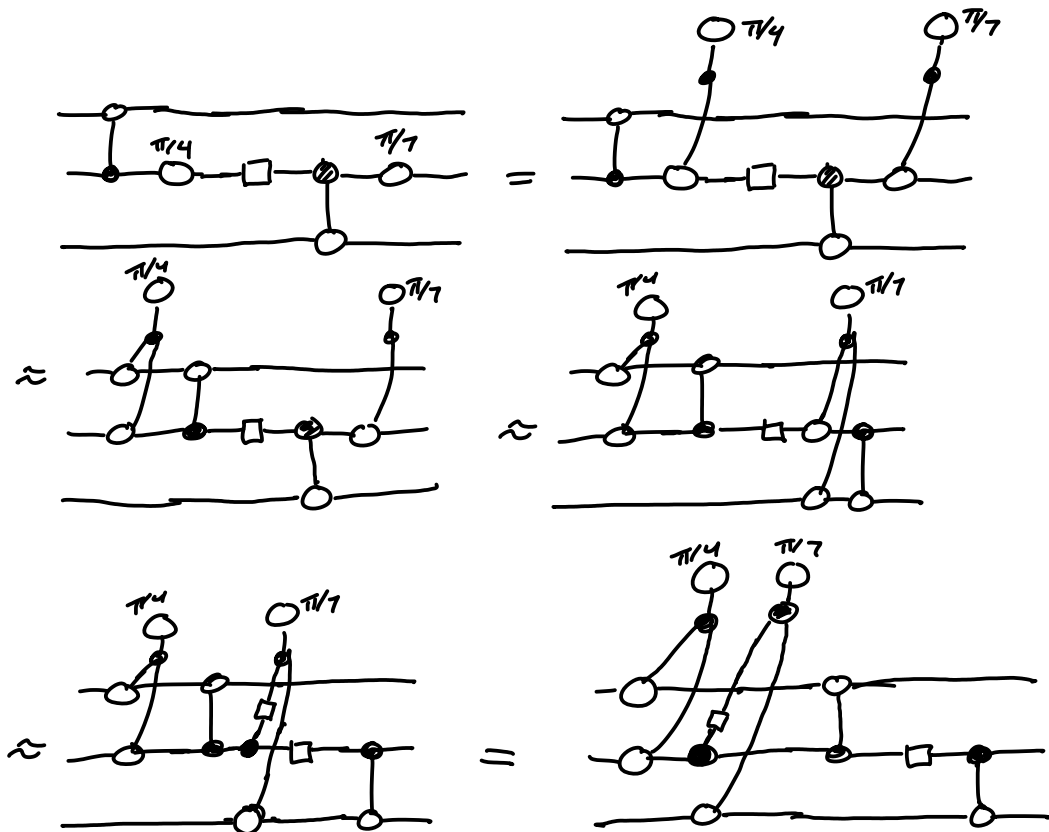
Cons: · CNOT count/depth is inconsistent.

* Better for CNOT count: Gray-synth [Amy, Azimzadeh, Mosca 2017]

Pauli Gadgets

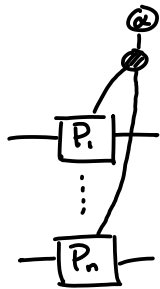
Clifford + Phase is a universal family.

Q: Can we move all the non-Clifford phases out?



PROP For $\vec{P} = P_1 \otimes \dots \otimes P_n$ with $P_i \in \{I, X, Y, Z\}$ the

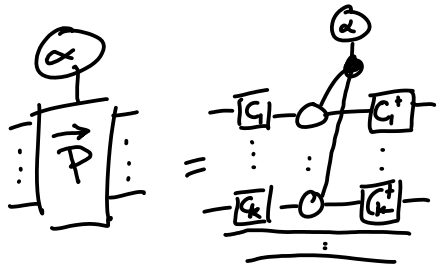
map:



where:
$$\begin{cases} \boxed{X} = \text{---} \text{---} \text{---} \\ \boxed{Y} = \text{---} \text{---} \text{---} \\ \boxed{Z} = \text{---} \text{---} \text{---} \\ \boxed{I} = \text{---} \end{cases}$$

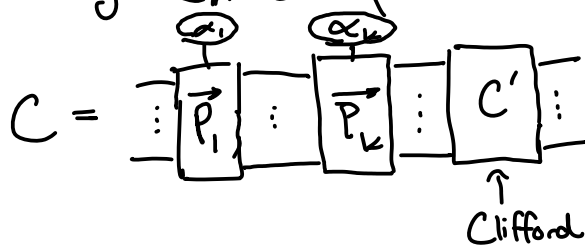
is unitary. It is called the Pauli gadget $\vec{P}(\alpha)$.

PF Note $\boxed{X} := \text{---} \text{---} \text{---}$ and $\boxed{Y} = \text{---} \text{---} \text{---}$. So



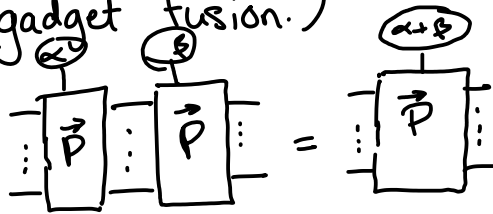
for Cliff. unitaries G_i . Since phase gadgets are unitary, so is $\vec{P}(\alpha)$. \square

Thm Any Clifford+phase circuit can be written as:

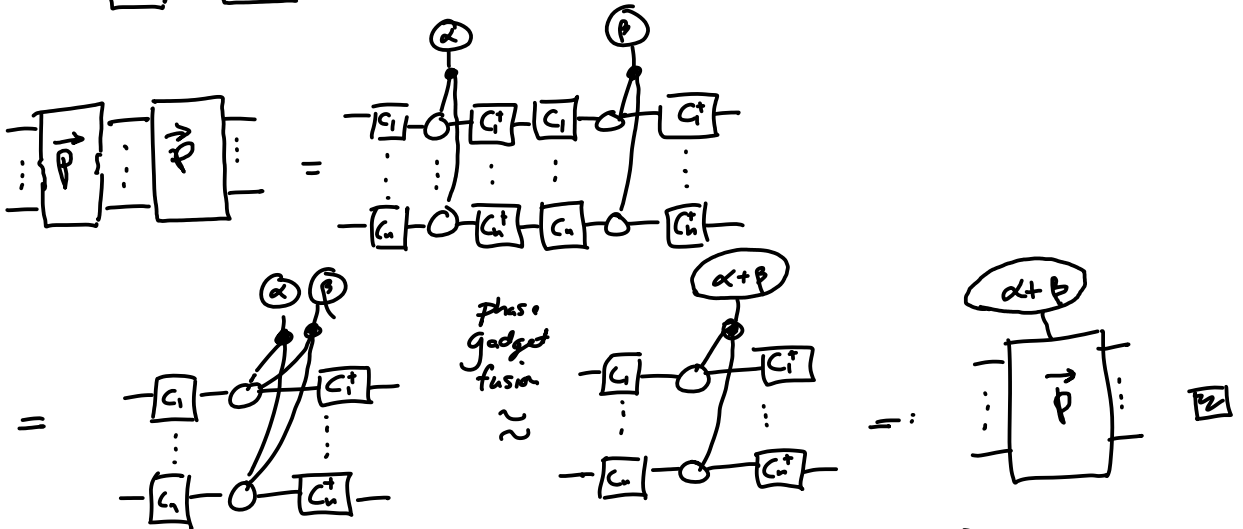


PF (Idea) • Show Pauli gadgets commute past all Clifford gates.
• Move phases out of C , one at a time. \square

Prop (Pauli gadget fusion.)



Pf



Prop For Paulis \vec{P}, \vec{Q} if $\vec{P}\vec{Q} = \vec{Q}\vec{P}$, then $\vec{P}(\alpha)\vec{Q}(\beta) = \vec{Q}(\beta)\vec{P}(\alpha)$.

Pf Exercise/ (Hint: it's complementarity!)
back

Algorithm Pauli "phase folding".

1. Compute Pauli gadget form of a circuit.
2. Commute PG's and combine phases where possible.
3. Merge PG's with Clifford phases into the Clifford part.
4. Repeat until no more reductions.
5. Extract circuit.*

* like with CNOT+phase, there are many options.

Q: What are Pauli gadgets?

A: Exponentials of Pauli matrices.

In general, matrix exponentials are defined as:

$$e^A := \sum_{k=0}^{\infty} \frac{A^k}{k!} \quad \leftarrow \text{Taylor series}$$

Special case: numbers $e^z = \sum_{k=0}^{\infty} \frac{z^k}{k!}$

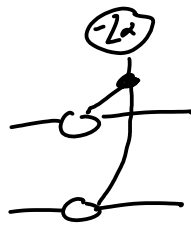
diagonal matrices:
$$e^{\text{diag}(a_1, \dots, a_n)} = \sum_{k=0}^{\infty} \frac{\text{diag}(a_1, \dots, a_n)^k}{k!}$$
$$= \sum_{k=0}^{\infty} \frac{\text{diag}(a_1^k, \dots, a_n^k)}{k!} = \text{diag}(e^{a_1}, \dots, e^{a_n})$$

Conjugation:
$$e^{U A U^\dagger} = \sum_k \frac{(U A U^\dagger)^k}{k!} = \sum_k U \frac{A^k}{k!} U^\dagger = U \sum_k \frac{A^k}{k!} U^\dagger$$
$$= U e^A U^\dagger.$$

Ex $Z \otimes Z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \otimes \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \begin{pmatrix} 1 & & & \\ & -1 & & \\ & & -1 & \\ & & & 1 \end{pmatrix}$

$U = e^{i\alpha Z \otimes Z} = \begin{pmatrix} e^{i\alpha} & & & \\ & e^{-i\alpha} & & \\ & & e^{-i\alpha} & \\ & & & e^{i\alpha} \end{pmatrix} \propto \begin{pmatrix} 1 & & & \\ & e^{-2i\alpha} & & \\ & & e^{-2i\alpha} & \\ & & & 1 \end{pmatrix}$

$U |xy\rangle = e^{-2i\alpha \cdot (x \otimes y)} |xy\rangle$



More generally:

THM $e^{-i\frac{\alpha}{2} Z \otimes \dots \otimes Z} =$

Cor $e^{-i\frac{\alpha}{2} \vec{P}} =$

Application: Hamiltonian simulation.

Time evolution: $|\Psi_t\rangle = e^{-itH} |\Psi_0\rangle$

Q: Can we design a circuit that implements e^{-itH} ?

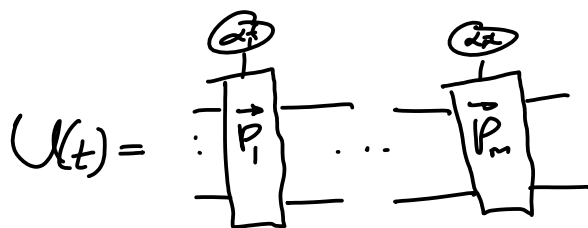
Observation:

Pauli's span the space of all self-adjoint operators on qubits.

$$H = \frac{1}{2} \sum_{j=1}^m \alpha_j \vec{P}_j$$

If all \vec{P}_j commute, then it's easy:

$$U = e^{-itH} = e^{-it\frac{\alpha_1}{2}\vec{P}_1} \dots e^{-it\frac{\alpha_m}{2}\vec{P}_m}$$



If they do not commute, this is still approximately true.

$$U(t) \approx t^2 K \left(\begin{array}{c} \alpha_1 t \\ \vdots \\ \vec{P}_1 \\ \vdots \\ \vec{P}_m \\ \vdots \end{array} \right)$$

The trick: make t very small!

$$e^{-itH} = \underbrace{\left(e^{-t/d H} \right)^d}_{\text{approximate this } d \text{ times}}$$

$$U\left(\frac{t}{d}\right)^d \approx d \cdot \left(\frac{t}{d}\right)^2 K \left(\begin{array}{c} \alpha_1 \frac{t}{d} \\ \vdots \\ \vec{P}_1 \\ \vdots \\ \vec{P}_m \\ \vdots \end{array} \right)^d$$

Error: $d \cdot \left(\frac{t}{d}\right)^2 K = \frac{t^2}{d} \cdot K \rightarrow 0$ as $d \rightarrow \infty$.

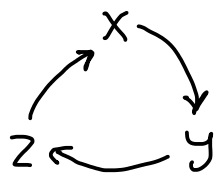
Lecture 14 | Pauli groups & Stabiliser Theory

The Pauli matrices:

$$X = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$Y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$$

$$Z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$



$$X^2 = Y^2 = Z^2 = I$$

$$XY = iZ$$

$$\Rightarrow YZ = iX, ZY = -iX$$

$$\Rightarrow XZ = -iY, YX = -iZ$$

$$\Rightarrow PQ = -QP \quad (P \neq Q, P, Q \in \{X, Y, Z\})$$

Def The n -qubit Pauli group

$$\mathcal{P}_n = \{ i^k P_1 \otimes \dots \otimes P_n \mid P_j \in \{I, X, Y, Z\}, k \in \{0, 1, 2, 3\} \}$$

We call $\vec{P} \in \mathcal{P}_n$ a Pauli string. It is self-adj. iff $k \in \{0, 2\}$ otherwise $\vec{P}^\dagger = -i\vec{P}$.

Prop $\forall \vec{P}, \vec{Q} \in \mathcal{P}_n, \vec{P}\vec{Q} = \pm\vec{Q}\vec{P}$.

Pf Follows from the fact that for all $P, Q \in \{I, X, Y, Z\}, PQ = \pm QP$. \square

Ex's Count the number of anti-commuting Paulis (even or odd):

$$(X \otimes X \otimes Y)(Z \otimes X \otimes I) = -(Z \otimes X \otimes I)(X \otimes X \otimes Y)$$

$$(X \otimes X \otimes Y)(Z \otimes I \otimes Z) = (Z \otimes I \otimes Z)(X \otimes X \otimes Y)$$

Let $\langle \vec{P}_1, \dots, \vec{P}_m \rangle$ be the subgroup of \mathcal{P}_n generated by products of \vec{P}_k .

Def A subgroup $S \subseteq \mathcal{P}_n$ stabilises a state $|\psi\rangle$ if $\forall \vec{P} \in S, \vec{P}|\psi\rangle = |\psi\rangle$ ($|\psi\rangle$ is a +1 e-vec of \vec{P})

Let $\text{Stab}(S) = \{ |\psi\rangle \mid \forall \vec{P} \in S, \vec{P}|\psi\rangle = |\psi\rangle \}$.

Prop $\text{Stab}(S)$ is a subspace of $(\mathbb{C}^2)^{\otimes n}$, called the stabiliser subspace.

Pf Show $\text{Stab}(S)$ is closed under linear combinations. $\forall \vec{P} \in S$:

$$\vec{P}(\alpha|\psi\rangle + \beta|\phi\rangle) = \alpha\vec{P}|\psi\rangle + \beta\vec{P}|\phi\rangle = \alpha|\psi\rangle + \beta|\phi\rangle. \quad \square$$

Def A subgroup $S \subseteq \mathcal{P}_n$ where $\text{Stab}(S) \neq \{0\}$ is called a stabiliser subgroup.

Prop If S is a stab. subgroup:

(1) $-I \notin S$

(2) $\forall \vec{P} \in S, \vec{P}^\dagger = \vec{P}$

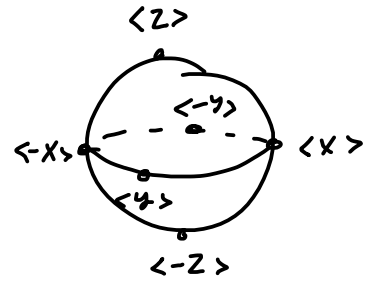
(3) S is commutative

Pf ⁽¹⁾ If $-I \in S$, then $(-I)|\psi\rangle = |\psi\rangle \Rightarrow -|\psi\rangle = |\psi\rangle$.

The only possibility is $|\psi\rangle = 0$. Then (1) \Rightarrow (2) and (2) \Rightarrow (3). \square

Ex $\mathcal{P}_1 = \{ i^k P \mid k \in \mathbb{Z}, P \in \{I, X, Y, Z\} \}$ has 6 stabiliser subgroups: $\langle X \rangle, \langle Y \rangle, \langle Z \rangle, \langle -X \rangle, \langle -Y \rangle, \langle -Z \rangle$

$$\begin{aligned}
 X|+\rangle &= |+\rangle & (-X)|-\rangle &= |-\rangle \\
 Y|+i\rangle &= |+i\rangle & (-Y)|-i\rangle &= |-i\rangle \\
 Z|0\rangle &= |0\rangle & (-Z)|\infty\rangle &= |\infty\rangle
 \end{aligned}$$



Pushin' PAULIS:

Thm For any Clifford unitary U , $\vec{P} \in \mathcal{P}_n$:

$$\boxed{U^\dagger} \boxed{\vec{P}} \boxed{U} = \boxed{\vec{Q}} \in \mathcal{P}_n.$$

Pf

Equivalently, we can "push" Paulis through:

$$\boxed{\vec{P}} \boxed{U} = \boxed{U} \boxed{\vec{Q}}$$

Every \vec{P} is a product of $\begin{matrix} \cdot \\ \hline \pi \\ \hline \cdot \end{matrix}$ and $\begin{matrix} \cdot \\ \hline \frac{\pi}{2} \\ \hline \cdot \end{matrix}$, so we can push through Clifford gates 1 at a time:

$$H: \quad \begin{matrix} \pi \\ \circ \end{matrix} \text{---} \square \text{---} = \text{---} \square \begin{matrix} \pi \\ \circ \end{matrix} \quad \begin{matrix} \pi \\ \circ \end{matrix} \text{---} \square \text{---} = \text{---} \square \begin{matrix} \pi \\ \circ \end{matrix}$$

$$\begin{aligned}
 S: \quad \begin{matrix} \pi/2 \\ \circ \end{matrix} \text{---} \begin{matrix} \pi \\ \circ \end{matrix} \text{---} &= \begin{matrix} \pi/2 \\ \circ \end{matrix} \text{---} \begin{matrix} \pi \\ \circ \end{matrix} \text{---} & \begin{matrix} \pi \\ \circ \end{matrix} \text{---} \begin{matrix} \pi/2 \\ \circ \end{matrix} \text{---} &= i \cdot \begin{matrix} -\pi/2 \\ \circ \end{matrix} \text{---} \begin{matrix} \pi \\ \circ \end{matrix} \text{---} \\
 & & &= i \cdot \begin{matrix} -\pi/2 \\ \circ \end{matrix} \text{---} \begin{matrix} \pi \\ \circ \end{matrix} \text{---} \begin{matrix} \pi \\ \circ \end{matrix} \text{---} \\
 & & &= \begin{matrix} \pi/2 \\ \circ \end{matrix} \text{---} \boxed{Y} \text{---}
 \end{aligned}$$

$$\begin{aligned}
 \text{CNOT:} \quad & \begin{matrix} \pi \\ \circ \end{matrix} \text{---} \begin{matrix} \circ \\ \bullet \end{matrix} \text{---} = \begin{matrix} \pi \\ \circ \end{matrix} \text{---} \begin{matrix} \pi \\ \circ \end{matrix} \text{---} & \begin{matrix} \circ \\ \bullet \end{matrix} \text{---} \begin{matrix} \circ \\ \bullet \end{matrix} \text{---} = \begin{matrix} \circ \\ \bullet \end{matrix} \text{---} \begin{matrix} \circ \\ \bullet \end{matrix} \text{---} \\
 & \begin{matrix} \circ \\ \bullet \end{matrix} \text{---} \begin{matrix} \pi \\ \circ \end{matrix} \text{---} = \begin{matrix} \circ \\ \bullet \end{matrix} \text{---} \begin{matrix} \pi \\ \circ \end{matrix} \text{---} & \begin{matrix} \pi \\ \circ \end{matrix} \text{---} \begin{matrix} \circ \\ \bullet \end{matrix} \text{---} = \begin{matrix} \pi \\ \circ \end{matrix} \text{---} \begin{matrix} \pi \\ \circ \end{matrix} \text{---}
 \end{aligned}$$



Stabiliser measurements.

Every s.a. \vec{P} defines 2 projectors:

$$\Pi_{\vec{P}}^{(0)} = \frac{1}{2}(\mathbb{I} + \vec{P}) \quad \Pi_{\vec{P}}^{(1)} = \frac{1}{2}(\mathbb{I} - \vec{P})$$



$$\Pi_{\vec{P}}^{(k)} = \frac{1}{2}(\mathbb{I} + (-1)^k \vec{P})$$

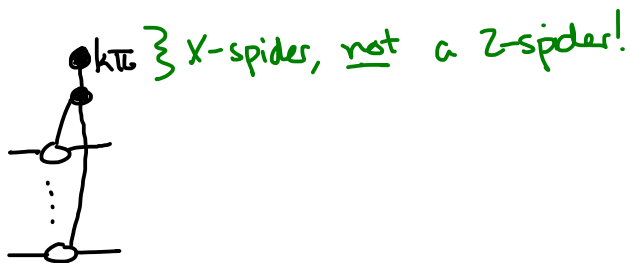
$$\Pi_{\vec{P}}^{(0)} + \Pi_{\vec{P}}^{(1)} = \frac{1}{2}(2 \cdot \mathbb{I}) = \mathbb{I}$$

So they define a measurement $\mathcal{M}_{\vec{P}} = \{ \Pi_{\vec{P}}^{(k)} \}_{k=0,1}$

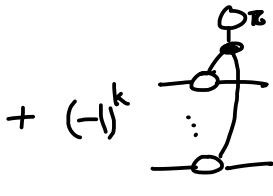
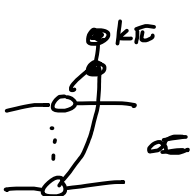
If $\vec{P} \in S$, a stabiliser subgp, $\mathcal{M}_{\vec{P}}$ is called a stabiliser measurement.

Graphically:

$$\Pi_{2^0-2^2}^{(k)} \propto$$



$$\overset{k\pi}{\circlearrowleft} = \overset{0}{\uparrow} + (-1)^k \overset{1}{\uparrow} = \frac{1}{\sqrt{2}}(\uparrow + (-1)^k \uparrow)$$



$$\propto \begin{array}{c} \text{---} \\ \vdots \\ \text{---} \end{array} + (-1)^k \begin{array}{c} \text{---} \\ \vdots \\ \text{---} \end{array} \propto \Pi_{2-2}^{(k)}$$

To get other Paulis, we can conjugate by LC's:

$$\begin{aligned} \square \text{---} \bigcirc_{\pi} \text{---} \square &= \text{---} \bigcirc_{\pi} \\ \bigcirc_{\pi/2} \text{---} \bigcirc_{\pi} \text{---} \bigcirc_{-\pi/2} &= i \cdot \text{---} \bigcirc_{\pi} \text{---} \bigcirc_{\pi} = \square \text{---} \bigcirc_{\pi} \end{aligned}$$

Pauli boxes

\square_P such that $\square_P^{k\pi} = \begin{cases} \text{---} & \text{if } k=0 \\ \square_P & \text{if } k=1 \end{cases}$ for $k \in \{I, X, Y, Z\}$.

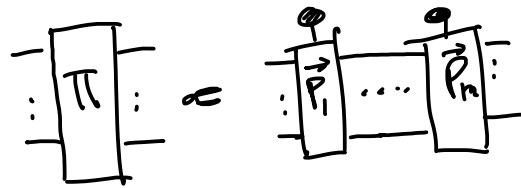
$$\begin{aligned} \square_I &= \frac{1}{\sqrt{2}} \cdot \bigcirc_{\pi} & \square_X &= \square \text{---} \bigcirc_{\pi} \text{---} \square \\ \square_Y &= \bigcirc_{\pi/2} \text{---} \bigcirc_{\pi} \text{---} \bigcirc_{-\pi/2} & \square_Z &= \bigcirc_{\pi} \end{aligned}$$

Prop For $\vec{P} = P_1 \otimes \dots \otimes P_n$, let:

$$\begin{array}{c} | \\ \vdots \\ \square_{\vec{P}} \\ \vdots \\ | \end{array} = \begin{array}{c} \sqrt{2}^{n-1} \cdot \bigcirc_{\pi} \\ \vdots \\ \square_{P_1} \\ \vdots \\ \square_{P_n} \end{array}$$

then $\begin{array}{c} \frac{1}{\sqrt{2}} \cdot \bigcirc_{\pi} \\ \vdots \\ \square_{\vec{P}} \\ \vdots \\ | \end{array} = \prod_{\vec{P}}^{(k)}$

LEM For $S = \langle \vec{P}_1, \dots, \vec{P}_m \rangle :$



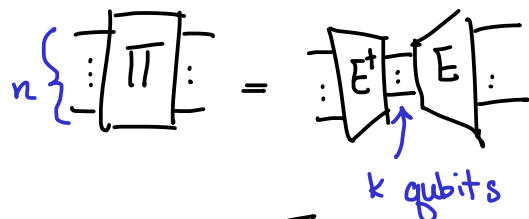
is a projector, and $\text{im}\Pi = \text{Stab}(S)$

Fundamental theorem of stabiliser theory

THM (FTST) For $S = \langle \vec{P}_1, \dots, \vec{P}_m \rangle \subseteq \mathcal{P}_n$ a stabiliser subgp. with m indep. generators:

$$\dim(\text{Stab}(S)) = 2^k \text{ for } k = n - m.$$

Pf (idea) Show we can split the projector Π :



for an isometry E . □

$k \left\{ \begin{array}{c} \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \end{array} \right\}_n$ is called an encoder for $\text{Stab}(S)$.

We will use it to treat $\text{Stab}(S)$ as a quantum error correcting code.

Def A stabiliser code is a subspace $\text{Stab}(S) \subseteq (\mathbb{C}^2)^{\otimes n}$.

for $S = \langle \underbrace{\vec{P}_1, \dots, \vec{P}_m}_{\text{indep.}} \rangle$ a stabiliser group.

It is characterised by 3 parameters:

Physical qubits: n
Logical qubits: k
Code distance: d

$$k \left\{ \begin{array}{c} \boxed{E} \\ \vdots \\ \vdots \end{array} \right\}_n$$

$$[[n, k, d]]$$

Def The weight $|\vec{Q}|$ of $\vec{Q} \in \mathcal{P}_n$ is the # of $Q_j \neq I$.

eg $|x \otimes y \otimes I| = 2$.

The code distance of $\text{Stab}(S)$ is the smallest weight > 0 of a Pauli str $\vec{Q} \notin S$ where $P\vec{Q} = \vec{Q}P \quad \forall P \in S$.

Stabiliser measurements:

$$\langle \Psi | \cdot | \Psi \rangle \in \text{Stab}(S)$$

Then perform $M_{\vec{p}_j} = \left\{ \begin{array}{c} s_j \cdot \pi \\ \vdots \\ \vec{p}_j \\ \vdots \end{array} \right\}_{s_j \in \{0,1\}}$

LEM $\begin{array}{c} | \\ \vdots \\ \vec{p} \\ \vdots \end{array} \begin{array}{c} | \\ \vdots \\ \vec{p} \\ \vdots \end{array} = \begin{array}{c} \cup \\ \vdots \\ \vec{p} \\ \vdots \end{array}$ and $\begin{array}{c} 0 \\ \vdots \\ \vec{p} \\ \vdots \end{array} = \begin{array}{c} \vdots \\ \vdots \end{array}$

Pf (Strong complementarity!)

Cor $\begin{array}{c} \pi \\ \vdots \\ \vec{p} \\ \vdots \end{array} \begin{array}{c} \pi \\ \vdots \\ \vec{p} \\ \vdots \end{array} = \emptyset$

Pf $\begin{array}{c} 0 \\ \vdots \\ \vec{p} \\ \vdots \end{array} \begin{array}{c} \pi \\ \vdots \\ \vec{p} \\ \vdots \end{array} = \begin{array}{c} \cup \\ \vdots \\ \vec{p} \\ \vdots \end{array} \propto \begin{array}{c} \pi \\ \vdots \\ \vec{p} \\ \vdots \end{array} = \emptyset.$

LEM If $\vec{P}\vec{Q} = (-1)^k \vec{Q}\vec{P}$ then:

$$\begin{array}{c} | \\ \vdots \\ \vec{Q} \\ \vdots \end{array} \begin{array}{c} | \\ \vdots \\ \vec{P} \\ \vdots \end{array} = \begin{array}{c} \bullet k\pi \\ \vdots \\ \vec{P} \\ \vdots \end{array} \begin{array}{c} | \\ \vdots \\ \vec{Q} \\ \vdots \end{array}$$

$$\begin{aligned} \text{Prob}(s_j=1 | |\Psi\rangle) &= \langle \Psi | \overset{\pi}{\uparrow} \vec{P}_j | \Psi \rangle \\ &= \langle \Psi | \vec{P}_j \overset{\pi}{\uparrow} \vec{P}_j | \Psi \rangle = 0. \end{aligned}$$

$$\Rightarrow \text{Prob}(s_j=0 | |\Psi\rangle) = 1.$$

Similarly, if \vec{Q} commutes w/ \vec{P}_j :

$$\begin{aligned} \text{Prob}(s_j=1 | |\Psi\rangle) &= \langle \Psi | \vec{Q} \overset{\pi}{\uparrow} \vec{P}_j \vec{Q} | \Psi \rangle \\ &= \langle \Psi | \vec{P}_j | \Psi \rangle = 0. \end{aligned}$$

$$\Rightarrow \text{Prob}(s_j=0) = 1$$

But if it anti-commutes:

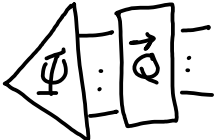
$$\begin{aligned} \text{Prob}(s_j=0) &= \langle \Psi | \vec{Q} \vec{P}_j \vec{Q} | \Psi \rangle \\ &= \langle \Psi | \overset{\pi}{\uparrow} \vec{P}_j | \Psi \rangle = 0! \end{aligned}$$

$$\Rightarrow \text{Prob}(s_j=1) = 1$$

\Rightarrow The outcome s_j detects error \vec{Q} . It is called an error syndrome.

An $[[n, k, d]]$ code can detect errors $|\vec{Q}| < d$.

It can also correct errors $|\vec{Q}| < \frac{d}{2}$.

1. Measure stabs:  \rightsquigarrow error syn. (s_1, \dots, s_m)

2. Guess some \vec{Q}' such that $\vec{Q}' \vec{P}_j = (-1)^{s_j} \vec{P}_j \vec{Q}'$.
and $|\vec{Q}'| < \frac{d}{2}$. ← "decoding" the error

Now: $\vec{Q}' \vec{Q} \vec{P}_j = (-1)^{s_j} \vec{P}_j \vec{Q}' \vec{Q} = \vec{P}_j \vec{Q}' \vec{Q}$.

$$|\vec{Q} \vec{Q}'| \leq |\vec{Q}| + |\vec{Q}'| < d$$

$$\Rightarrow \vec{Q} \vec{Q}' \in S$$

3. Apply correction:

